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Time schedule

The contribution should focus on theories, principles and developments which have been explicitly developed for robots (terrestrial, aerial), and carried sensor systems for environmental surveillance, risky interventions, in the Humanitarian De-Mining in particular

An **abstract** of approximately 300 words (in English) should be received not later than **.15 March 2012**
Electronic submissions of the abstracts (Word, PSF, PDF-files) should be e-mailed to:

nikola.pavkovic@ctro.hr and
Yvan.baudoin@rma.ac.be

- ⌘ Final selection and invitation of participants:
March, 30, 2012
- ⌘ Receipt full ready **e-papers**:
April, 15, 2012

Organization Committee

Workshop

Co-Chair:

Prof. Yvan Baudoin, RMA, Brussels.
MSc Nikola Pavkovic, CROMAC-CTDT Director

Workshop inquiries to:

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10th IARP Workshop Robotics and Mechanical assistance in Humanitarian De-mining and Similar risky interventions

HUDEM'2012

24-26 April, 2012

Coupled with the
[9th International Humanitarian Demining Symposium](#)

**Šibenik
Croatia
Call for Abstracts**



Background

Robotics solutions properly sized with suitable modularized mechanized structure and well adapted to local conditions of dangerous unstructured areas can greatly improve the safety of personnel as well as the work efficiency, productivity and flexibility. Solving this problem presents challenges in robotic mechanics and mobility, sensors and sensor fusion, autonomous or semi autonomous navigation and machine intelligence.

The workshop will review and discuss the available technologies, their limitations, their adaptability to different environmental natural or artificial calamities (humanitarian demining (OTTAWA convention, OSLO convention including the detection of sub-munitions) and discusses the development efforts to automate tasks related to detection / interventions processes wherever possible through the use of Robotics Systems and other technologies. The FP7 project TIRAMISU will be introduced.

Scope and Topics

Specific topics include but are not limited to:

- ◆ Tele-operations
- ◆ Mobile Robotics Systems (Design, control, command) for unstructured environments (UGV,UAV, multi-robotics cooperation)
- ◆ Conventional and Autonomous Hybrid Vehicles
- ◆ Sensors and sensor fusion for detection as well as for robot localization
- ◆ Demonstrators – Tests Results
- ◆ Human Machine Interface

The workshop will also review and discuss the available risky intervention/environmental surveillance technologies along with their limitations and discusses the development efforts to automate tasks related to detection / decontamination / neutralization process wherever possible through robotization.

Other Specific topics thus include but are not limited to:

- Inspection of fire or crisis grounds
- CBRN-E threats
- Map building and reconstruction
- Networked crisis management tools
- Remote controlled, semi-autonomous, autonomous robot navigation
- Victim Detection
- Swarm of robots
- Crisis Management Information Systems

IARP Sponsoring countries

Belgium,Canada, Korea, Poland, Russia, Spain

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G.S.Virk

Venue

The workshop will take place in **Šibenik**

By establishing the mine action system in Croatia, the Croatian Mine Action Center (CROMAC) created preconditions to engage in research and development and improvement of mine action techniques, technology and methods, testing of machines, mine detection dogs and handlers, testing and field evaluation of modern technologies, education and expert assistance to the countries in the Region and wider

