Danial Hawari, M.Sc., B.Eng.

Brussels, Belgium • +32663803319 • www.linkedin.com/in/danialhawari • danial.hawari@outlook.com "Research Engineer" | "Network Engineer" | "Cloud Engineer"

Educational Backgrounds

Hochschule Karlsruhe, Germany & Universidad de Oviedo, Spain

Erasmus Mundus Joint Master's Degree in Mechatronics Engineering

Relevant Coursework: Secured Cyber-Physical System (Cybersecurity), Autonomous Micro-Mechatronics System, Industrial Mechatronics System, Artificial Intelligence, Microcontroller Technology & Energy Efficiency, Industrial Robotics, Construction & Manufacturing, Control Systems Implementation, Industrial Electronics for Mechatronics Systems, Advanced Mechatronic Systems Design & Analysis, Serial Product Manufacturing, Automation

Hochschule Karlsruhe, Germany & University Malaysia Pahang, Malaysia

Dual Bachelor's Degree (Honors) in Mechatronics Engineering

February 2020

Relevant Coursework: Hybrid Integration, Electronic in Mechatronics Systems, Information System, Cleanroom Technology, Control System Engineering, Product Development & Design, Optoelectronics, Quality Inspection, Quality Management, Software Engineering, Computer Programming, Sensor & Instrumentation Systems, Industrial Automation, SMD Technology, Micro-Computer Technology, Numerical Programming, Programming for Engineer, Mechanical & Electrical Components, CAD Modelling, Mechanics of Materials, Manufacturing Processes

Technical Projects

| Development of Cyber-Physical System | March 2022 – August 2022 |
|--|--|
| An IoT gateway device that can communicate with the embedded Jetboard | system via BLE and connect to the |
| Internet via Wi-Fi/GSM with MQTT/HTTP was developed so that the cur | stomers can access the Jetboard status |
| • Designed and fabricated an embedded IoT gateway device for the self- | sufficient electric Jetboard system |
| • Developed a full-stack cloud application for remote monitoring and cost | ntrolling of the Jetboard |
| Development of Intelligent Crutch | September 2021 – February 2022 |
| The intelligent crutch, equipped with weight measurement sensors and feed | lback actuators, and its smartphone |
| application was developed to revolutionize the conventional crutch to prote | ect patients from injuring themselves |
| • Developed Intelligent Crutch smartphone app that can communicate w monitor the load on the affected limb and analyze gait patterns from the | with the crutch via Bluetooth to the obtained sensor data |
| • Designed the communication system between both crutches and between | een a crutch and the smartphone app |
| http://hit-karlsruhe.de/hit-info/info-ss21/intelligent-crutch/index.htm | nl |
| Development of Corona Ventilator Web Application | March 2021 – September 2021 |
| An affordable and easy-to-fabricate corona ventilator alternative was develop to monitor the patient status in a real-time manner to cope with the high de medical infrastructure such as in third-world countries | oped together with its Web application emand for places with mediocre |
| • Researched and redeveloped Web app based on Django framework tha plotting graphs, has admin and user management features, and patient l | it can generate high-performance history database |
| • Researched and redeveloped the embedded system to eliminate any cor system can send sensor data faster to the Internet | nmunication bottleneck so that the |
| Alternative project: http://www.hit-karlsruhe.de/hit-info/info-ws20/8 WebApp/TapToHomepage.html | x8-App/8x8- |
| Development of Autonomous Vehicle Model | September 2020 – June 2021 |
| A superior autonomous vehicle model than the previous model was develop | ped to participate in the TU |
| Braunschweig Carolo Cup Competition 2022 on behalf of the university | |
| • Replaced the previous system that runs on NVIDIA Jetson TX1 with I operates on Linux Ubuntu 20.04 OS, with ROS, and OpenCV depended | ntel NUC that has a system that encies |
| • Redeveloped the image processing system that can run without using C hardware with better image processing efficiency and the car was able t | CUDA architecture or CUDA GPU o navigate itself faster on the road |
| https://www.h-ka.de/die-hochschule-karlsruhe/aktuelles/news/2020/ hochschule-karlsruhe-am-13-carolo-cup-2020 | erfolgreiche-teilnahme-der- |

August 2022

March 2022 Amount 2022

Lampuga GmbH Rastatt, Baden-Wuerttemberg Embedded System Engineer - Working Student March 2022 - August 2022 Designed and developed alternative IoT solutions as an added value for the future product • Tested and validated Jetboard wireless communication system to prove the product robustness and quality Hochschule Karlsruhe Karlsruhe, Baden-Wuerttemberg May 2020 - May 2021 Research Assistant Supervised international projects "MYiTOPS" and other student projects • Prepared teaching materials and taught "Communication Protocol & Cloud System" Redeveloped Gas Engine Lab energy system with IoT technology for better control and efficiency **Intel Microelectronics** Bayan Lepas, Penang System on Chip Design Engineer - Intern July 2018 - Jan 2019 Developed automation scripts to increase productivity during the RTL design process Analyzed and debugged RTL for PCH in Comet Lake & Tiger Lake projects to create a better motherboard Leadership Experience Student Representative - Germany, EU4M September 2020 – August 2022 Organized and assisted matters related to student affairs https://www.eu4m.eu/consortium/organization Team Leader, MYiTOPS March 2019 - September 2019 Pioneered and led international teams comprise of German & Malaysian students to complete the projects https://www.h-ka.de/en/ikku/gas-engine-technology/myitops Computer Skills Programming Language - Python, Perl, PHP, SQL, HTML, JavaScript, Dart, Git, TCL, Bash, PLC, C++, C Microcontroller – Arduino, ESP32, Raspberry Pi, myRIO, NVIDIA Jetson, BeagleBone Black, Intel NUC/UP2, STM32WB Machine Learning - OpenCV, TensorFlow, Google Cloud ML, Keras, PyTorch, Scikit-Learn, Anaconda Computation & Simulation – MATLAB & Simulink, ANSYS, Flexsim, MoldFlow, Gazebo, LabView, KUKA.Sim Mechanical Design – Solidworks, Fusion 360, CATIA, Inventor, AutoCAD, Blender Electrical Design - Altera Quartus, Modelsim, Fritzing, Protheus, PSpice, Eagle, EasyEDA, KiCad EDA User Interface Design - Web App (BootStrap, Django, .NET, SQLite) & Native App (Android Studio, QT, PyCharm – PyQT5, MIT App Inventor, Flutter) Media Design - Adobe Creative Cloud Cloud Experience - Google Cloud, Amazon AWS, Microsoft Azure, DigitalOcean, BWCloud, PythonAnywhere IDE Experience - Linux (Ubuntu), Visual Studio /Code, PlatformIO, Atom, Jupyter, Docker, Google Colab, ROS Languages Spanish - Good proficiency in spoken and written language, B1+ level German – Good proficiency in spoken and written language, B2 level English - Highly proficient in spoken and written language, C1 level

Malay – Native language

Achievements

Work Experience

| DAAD Prize 2021 – German Academic Exchange Service | October 2021 |
|---|----------------|
| VDI University Prize 2020 – Association of German Engineers Karlsruhe | September 2020 |
| Top 10 Best Practice Projects – Stifterverband MINTClub MINTChallenge: MINTDigital 2020 | June 2020 |
| Erasmus Mundus Scholarship – Education, Audiovisual & Culture Executive Agency (EACEA) | March 2020 |
| Global Problem Solver – NASA Space Apps COVID-19 Challenge 2020 | May 2020 |
| 3 rd place – AON Hacktuarial Hackathon 2019 | July 2019 |
| 2 nd place – Intel Industry-University Challenge 2018 | November 2018 |
| TRIZ Level 1 Practitioner – The International TRIZ Association | September 2018 |
| Bursary Programme Scholarship 2016-2020 – Yayasan Sime Darby | August 2016 |

Interests

Internet of Things, Artificial Intelligence, Cyber-Physical System, Automation, Robotics, Communication, Web Application, Cloud Application, Mechatronics, Animatronics, Embedded System

References

Prof. Dr. -Ing. Robert Weiß

Hochschule Karlsruhe, Germany Dean Faculty of Mechanical Engineering and Mechatronics robert.weiss@h-ka.de +49 721 9251 916

Prof. Dr. -Ing. Maurice Kettner

Hochschule Karlsruhe, Germany Dean of Automotive Technology Faculty of Mechanical Engineering and Mechatronics maurice.kettner@h-ka.de +49 721 925 1845

Prof. Miguel Ángel José Prieto

Universidad de Oviedo, Spain EU4M Coordinator mike@uniovi.es +34 985 182 567

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